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# De transformatione functionum duas variables involventium dum earum loco aliae binae variables introducuntur

Leonhard Euler

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DE TRANSFORMATIONE FUNCTIONUM,  
DUAS VARIABLES INVOLVENTIUM,

DUM EARUM LOCO ALIAE BINAЕ VARIABLES INTRODUCUNTUR.

AUCTORE

L. E U L E R O.

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Conventui exhib. die 18 Octobris 1779.

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§. 1. Etsi hoc argumentum in tertio volumine Institutionum mearum calculi integralis jam fusius pertractavi, tamen hic methodum sum traditurus, cujus ope tales transformationes multo facilius expediri queant. Si igitur  $z$  fuerit functio quaecunque binarum variabilium  $x$  et  $y$ , harumque loco aliae binae variables quaecunque  $t$  et  $u$  in calculum introducuntur, quaestio huc redit: quamadmodum omnes formulae differentiales, ex proposita functione  $z$  oriundae, cujusmodi sunt  $(\frac{\partial z}{\partial x})$ ;  $(\frac{\partial z}{\partial y})$ ;  $(\frac{\partial^2 z}{\partial x^2})$ ;  $(\frac{\partial^2 z}{\partial x \partial y})$ ;  $(\frac{\partial^2 z}{\partial y^2})$ ; etc. per binas novas variables  $t$  et  $u$  exprimantur?

§. 2. Quoniam relatio inter binas variables  $x$  et  $y$ , respectu novarum  $t$  et  $u$ , cognita assumitur, non solum binae priores  $x$  et  $y$  tanquam functiones binarum posteriorum  $t$  et  $u$  spectari poterunt, sed etiam istae  $t$  et  $u$

erunt certae functiones binarum priorum  $x$  et  $y$ , quam relationem per sequentes formulas differentiales repraesentabo:

$$\partial t = P \partial x + Q \partial y \text{ et } \partial u = R \partial x + S \partial y,$$

quae ut sint determinatae, necesse est fieri:  $(\frac{\partial P}{\partial y}) = (\frac{\partial Q}{\partial x})$  et  $(\frac{\partial R}{\partial y}) = (\frac{\partial S}{\partial x})$ ; ubi litterae  $P, Q, R, S$  non solum tanquam functiones ipsarum  $x$  et  $y$  sed etiam ipsarum  $t$  et  $u$  spectari poterunt, ob cognitam rationem, quam hae binae variables inter se tenent.

§. 3. His positis primo investigemus valores formularum differentialium primi gradus, quae sunt  $(\frac{\partial z}{\partial x})$  et  $(\frac{\partial z}{\partial y})$ , quos accipient per novas variables  $t$  et  $u$ . Ac primo quidem, cum sit tam  $\partial z = \partial x (\frac{\partial z}{\partial x}) + \partial y (\frac{\partial z}{\partial y})$  quam  $\partial z = \partial t (\frac{\partial z}{\partial t}) + \partial u (\frac{\partial z}{\partial u})$ , loco  $\partial t$  et  $\partial u$  valores ante stabilitos scribendo prodibit ista aequatio:

$$\partial x (\frac{\partial z}{\partial x}) + \partial y (\frac{\partial z}{\partial y}) = P \partial x (\frac{\partial z}{\partial t}) + Q \partial y (\frac{\partial z}{\partial t}) + R \partial x (\frac{\partial z}{\partial u}) + S \partial y (\frac{\partial z}{\partial u}).$$

Hic evidens est utrinque terminos, eodem differentiali  $\partial x$  vel  $\partial y$  affectos, seorsim inter se aequari debere; unde colligimus has duas aequationes:

$$\text{I. } (\frac{\partial z}{\partial x}) = P (\frac{\partial z}{\partial t}) + R (\frac{\partial z}{\partial u})$$

$$\text{II. } (\frac{\partial z}{\partial y}) = Q (\frac{\partial z}{\partial t}) + S (\frac{\partial z}{\partial u}).$$

ubi jam litterae  $P, Q, R, S$  tanquam functiones ipsarum  $t$  et  $u$  spectari poterunt, sicque formulae differentiales  $(\frac{\partial z}{\partial x})$  et  $(\frac{\partial z}{\partial y})$  per binas novas  $(\frac{\partial z}{\partial t})$  et  $(\frac{\partial z}{\partial u})$  exprimuntur.

§. 4. Multo autem difficilius est hinc valores formularum differentialium secundi gradus, quae sunt  $(\frac{\partial \partial z}{\partial x^2})$ ;  $(\frac{\partial \partial z}{\partial x \partial y})$ ;  $(\frac{\partial \partial z}{\partial y^2})$  elicere, id quod tamen sequenti modo satis commode praestari poterit. Incipiamus a prima harum formularum  $(\frac{\partial \partial z}{\partial x^2})$ , quae oritur ex formula  $(\frac{\partial z}{\partial x})$ , si ea differentietur, sumto  $\partial y = 0$ , et differentiale denuo per  $\partial x$  dividatur. At vero, sumto  $\partial y = 0$ , ex formulis principalibus erit  $\partial t = P \partial x$  et  $\partial u = R \partial x$ , unde fit  $(\frac{\partial t}{\partial x}) = P$  et  $(\frac{\partial u}{\partial x}) = R$ . Hinc tantum opus est ut formulae  $P(\frac{\partial z}{\partial t}) + R(\frac{\partial z}{\partial u})$  differentiale per  $\partial x$  dividatur, pro casu scilicet  $\partial y = 0$ . Cum autem jam  $P$  et  $Q$  sint functiones binarum  $t$  et  $u$ , earum differentia talem habebunt formam:  $M \partial t + N \partial u$ ; unde ergo, ob  $(\frac{\partial t}{\partial x}) = P$  et  $(\frac{\partial u}{\partial x}) = R$ , pro  $\frac{\partial P}{\partial x}$  habebimus  $MP + NR$ . Simili modo etiam  $\frac{\partial Q}{\partial x}$  ad functionem ipsarum  $t$  et  $u$  reducetur, quae reductio cum per se sit manifesta, in calculo retineamus  $\frac{\partial P}{\partial x}$  et  $\frac{\partial Q}{\partial x}$ . Interim tamen, cum sit  $M = (\frac{\partial P}{\partial t})$  et  $N = (\frac{\partial P}{\partial u})$ , erit  $\frac{\partial P}{\partial x} = P(\frac{\partial P}{\partial t}) + R(\frac{\partial P}{\partial u})$ ; similique modo erit  $(\frac{\partial Q}{\partial x}) = P(\frac{\partial Q}{\partial t}) + R(\frac{\partial Q}{\partial u})$ .

§. 5. Superest ergo ut etiam formulas  $(\frac{\partial z}{\partial t})$  et  $(\frac{\partial z}{\partial u})$  eadem lege tractemus. Cum igitur in genere sit:

$$\partial \cdot (\frac{\partial z}{\partial t}) = \partial t (\frac{\partial \partial z}{\partial t^2}) + \partial u (\frac{\partial \partial z}{\partial t \partial u}),$$

hoc per  $\partial x$  divisum, ob  $(\frac{\partial t}{\partial x}) = P$  et  $(\frac{\partial u}{\partial x}) = R$ , evadet

$$P(\frac{\partial \partial z}{\partial t^2}) + R(\frac{\partial \partial z}{\partial t \partial u}) = \frac{\partial \cdot \frac{\partial z}{\partial t}}{\partial x},$$

Simili modo  $\frac{1}{\partial x} \partial \cdot \left( \frac{\partial z}{\partial u} \right) = P \left( \frac{\partial \partial z}{\partial t \partial u} \right) + R \left( \frac{\partial \partial z}{\partial u^2} \right)$ . His ergo observatis erit:

$$\begin{aligned} \left( \frac{\partial \partial z}{\partial x^2} \right) &= \frac{\partial P}{\partial x} \left( \frac{\partial z}{\partial t} \right) + PP \left( \frac{\partial \partial z}{\partial t^2} \right) + PR \left( \frac{\partial \partial z}{\partial t \partial u} \right) \\ &+ \frac{\partial R}{\partial x} \left( \frac{\partial z}{\partial u} \right) + RP \left( \frac{\partial \partial z}{\partial t \partial u} \right) + RR \left( \frac{\partial \partial z}{\partial u^2} \right), \end{aligned}$$

quae formula contrahitur in hanc:

$$\begin{aligned} \left( \frac{\partial \partial z}{\partial x^2} \right) &= \frac{\partial P}{\partial x} \left( \frac{\partial z}{\partial t} \right) + \frac{\partial R}{\partial x} \left( \frac{\partial z}{\partial u} \right) + PP \left( \frac{\partial \partial z}{\partial t^2} \right) \\ &+ 2PR \left( \frac{\partial \partial z}{\partial t \partial u} \right) + RR \left( \frac{\partial \partial z}{\partial u^2} \right). \end{aligned}$$

§. 6. Aggrediamur jam secundam formulam  $\left( \frac{\partial \partial z}{\partial x \partial y} \right)$ , quae primo ex formula  $\frac{\partial z}{\partial x}$  derivari potest, eam scilicet differentiando, sola  $y$  pro variabili sumta, ita ut sit  $\partial x = 0$ . Deinde etiam illa formula derivari potest ex formula  $\left( \frac{\partial z}{\partial y} \right)$ , eam differentiando, sumta sola  $x$  variabili, ideoque  $\partial y = 0$ . Evolvamus primo hoc modo formulam  $\left( \frac{\partial z}{\partial x} \right)$ , et quia sumto  $\partial x = 0$  fit  $\partial t = Q \partial y$  et  $\partial u = S \partial y$ , ideoque  $\left( \frac{\partial t}{\partial y} \right) = Q$  et  $\left( \frac{\partial u}{\partial y} \right) = S$ , hinc ex quantitibus  $P$  et  $R$  oriuntur formulae  $\frac{\partial P}{\partial y}$  et  $\frac{\partial R}{\partial y}$ , quarum valores, uti casu praecedente, per se erunt cogniti. Erit scil.  $\frac{\partial P}{\partial y} = Q \left( \frac{\partial P}{\partial t} \right) + S \left( \frac{\partial P}{\partial u} \right)$ ; similique modo erit  $\frac{\partial R}{\partial y} = Q \left( \frac{\partial R}{\partial t} \right) + S \left( \frac{\partial R}{\partial u} \right)$ , quarum autem loco retineamus formas  $\frac{\partial P}{\partial y}$  et  $\frac{\partial R}{\partial y}$ . Porro vero habebimus:

$$\begin{aligned} \frac{1}{\partial y} \partial \cdot \left( \frac{\partial z}{\partial t} \right) &= Q \left( \frac{\partial \partial z}{\partial t^2} \right) + S \left( \frac{\partial \partial z}{\partial t \partial u} \right) \\ \frac{1}{\partial y} \partial \cdot \left( \frac{\partial z}{\partial u} \right) &= Q \left( \frac{\partial \partial z}{\partial t \partial u} \right) + S \left( \frac{\partial \partial z}{\partial u^2} \right). \end{aligned}$$

His igitur colligendis reperiemus:

$$\begin{aligned} \left(\frac{\partial \partial z}{\partial x \partial y}\right) &= \frac{\partial P}{\partial y} \left(\frac{\partial z}{\partial t}\right) + PQ \left(\frac{\partial \partial z}{\partial t^2}\right) + PS \left(\frac{\partial \partial z}{\partial t \partial u}\right) \\ &+ \frac{\partial R}{\partial y} \left(\frac{\partial z}{\partial u}\right) + QR \left(\frac{\partial \partial z}{\partial t \partial u}\right) + RS \left(\frac{\partial \partial z}{\partial u^2}\right), \end{aligned}$$

quam etiam hoc modo exprimere licet:

$$\begin{aligned} \left(\frac{\partial \partial z}{\partial x \partial y}\right) &= \frac{\partial P}{\partial y} \left(\frac{\partial z}{\partial t}\right) + \frac{\partial R}{\partial y} \left(\frac{\partial z}{\partial u}\right) \\ &+ PQ \left(\frac{\partial \partial z}{\partial t^2}\right) + (PS + QR) \left(\frac{\partial \partial z}{\partial t \partial u}\right) + RS \left(\frac{\partial \partial z}{\partial u^2}\right). \end{aligned}$$

§. 7. Eundem autem valorem etiam ex altera formula  $\left(\frac{\partial z}{\partial y}\right) = Q \left(\frac{\partial z}{\partial t}\right) + S \left(\frac{\partial z}{\partial u}\right)$  elicere licebit, eam differentiendo, sumta sola  $y$  variabili, ideoque  $\partial y = 0$ ; unde fit  $\left(\frac{\partial t}{\partial x}\right) = P$  et  $\left(\frac{\partial u}{\partial x}\right) = R$ . Hinc igitur primo habemus  $P \left(\frac{\partial Q}{\partial t}\right) + R \left(\frac{\partial Q}{\partial u}\right) = \frac{\partial Q}{\partial x}$ , similique modo  $\frac{\partial S}{\partial x} = P \left(\frac{\partial S}{\partial t}\right) + R \left(\frac{\partial S}{\partial u}\right)$ . Deinde erit uti in primo casu:

$$\begin{aligned} \frac{1}{\partial x} \partial \cdot \left(\frac{\partial z}{\partial t}\right) &= P \left(\frac{\partial \partial z}{\partial t^2}\right) + R \left(\frac{\partial \partial z}{\partial t \partial u}\right) \text{ et} \\ \frac{1}{\partial x} \partial \cdot \left(\frac{\partial z}{\partial u}\right) &= P \left(\frac{\partial \partial z}{\partial t \partial u}\right) + R \left(\frac{\partial \partial z}{\partial u^2}\right), \end{aligned}$$

quibus collectis orietur:

$$\begin{aligned} \left(\frac{\partial \partial z}{\partial x \partial y}\right) &= \frac{\partial Q}{\partial x} \left(\frac{\partial z}{\partial t}\right) + PQ \left(\frac{\partial \partial z}{\partial t^2}\right) + QR \left(\frac{\partial \partial z}{\partial t \partial u}\right) \\ &+ \frac{\partial S}{\partial x} \left(\frac{\partial z}{\partial u}\right) + PS \left(\frac{\partial \partial z}{\partial t \partial u}\right) + RS \left(\frac{\partial \partial z}{\partial u^2}\right), \end{aligned}$$

quae etiam hoc modo repraesentari potest:

$$\begin{aligned} \left(\frac{\partial \partial z}{\partial x \partial y}\right) &= \frac{\partial Q}{\partial x} \left(\frac{\partial z}{\partial t}\right) + \frac{\partial S}{\partial x} \left(\frac{\partial z}{\partial u}\right) \\ &+ PQ \left(\frac{\partial \partial z}{\partial t^2}\right) + (QR + PS) \left(\frac{\partial \partial z}{\partial t \partial u}\right) + RS \left(\frac{\partial \partial z}{\partial u^2}\right), \end{aligned}$$

quae formula cum praecedente egregie convenit: initio enim jam notavimus esse  $\frac{\partial P}{\partial y} = \frac{\partial Q}{\partial x}$  et  $\frac{\partial R}{\partial y} = \frac{\partial S}{\partial x}$ .

§. 8. Tertia denique formula  $\left(\frac{\partial \partial z}{\partial y^2}\right)$  derivari debet ex formula  $\left(\frac{\partial z}{\partial y}\right) = Q \left(\frac{\partial z}{\partial t}\right) + S \left(\frac{\partial z}{\partial u}\right)$ , sumendo  $\partial x = 0$ , unde fit

$\frac{\partial t}{\partial y} = Q$  et  $\frac{\partial u}{\partial y} = S$ . Hinc ergo fiet

$$\frac{\partial Q}{\partial y} = Q \left( \frac{\partial Q}{\partial t} \right) + S \left( \frac{\partial Q}{\partial u} \right) \text{ et } \frac{\partial S}{\partial y} = Q \left( \frac{\partial S}{\partial t} \right) + S \left( \frac{\partial S}{\partial u} \right).$$

Deinde erit  $\frac{1}{\partial y} \partial \cdot \frac{\partial z}{\partial t} = Q \left( \frac{\partial \partial z}{\partial t^2} \right) + S \left( \frac{\partial \partial z}{\partial t \partial u} \right)$

$$\frac{1}{\partial y} \partial \cdot \frac{\partial z}{\partial u} = Q \left( \frac{\partial \partial z}{\partial t \partial u} \right) + S \left( \frac{\partial \partial z}{\partial u^2} \right),$$

quibus collectis fiet:

$$\begin{aligned} \left( \frac{\partial \partial z}{\partial y^2} \right) &= \frac{\partial Q}{\partial y} \left( \frac{\partial z}{\partial t} \right) + QQ \left( \frac{\partial \partial z}{\partial t^2} \right) + QS \left( \frac{\partial \partial z}{\partial t \partial u} \right) \\ &+ \frac{\partial S}{\partial y} \left( \frac{\partial z}{\partial u} \right) + QS \left( \frac{\partial \partial z}{\partial t \partial u} \right) + SS \left( \frac{\partial \partial z}{\partial u^2} \right), \end{aligned}$$

sive concinnius:

$$\begin{aligned} \frac{\partial \partial z}{\partial y^2} &= \frac{\partial Q}{\partial y} \left( \frac{\partial z}{\partial t} \right) + \frac{\partial S}{\partial y} \left( \frac{\partial z}{\partial u} \right) \\ &+ QQ \left( \frac{\partial \partial z}{\partial t^2} \right) + 2QS \left( \frac{\partial \partial z}{\partial t \partial u} \right) + SS \left( \frac{\partial \partial z}{\partial u^2} \right). \end{aligned}$$

§. 9. Istos jam valores pro formulis differentialibus secundi gradus inventos heic uni obtutui exponamus:

$$\begin{aligned} \text{I. } \left( \frac{\partial \partial z}{\partial x^2} \right) &= \frac{\partial P}{\partial x} \left( \frac{\partial z}{\partial t} \right) + \frac{\partial R}{\partial x} \left( \frac{\partial z}{\partial u} \right) \\ &+ PP \left( \frac{\partial \partial z}{\partial t^2} \right) + 2PR \left( \frac{\partial \partial z}{\partial t \partial u} \right) + RR \left( \frac{\partial \partial z}{\partial u^2} \right), \end{aligned}$$

$$\begin{aligned} \text{II. } \left( \frac{\partial \partial z}{\partial x \partial y} \right) &= \frac{\partial P}{\partial y} \left( \frac{\partial z}{\partial t} \right) + \frac{\partial R}{\partial y} \left( \frac{\partial z}{\partial u} \right) \\ &+ PQ \left( \frac{\partial \partial z}{\partial t^2} \right) + (PS + QR) \left( \frac{\partial \partial z}{\partial t \partial u} \right) + RS \left( \frac{\partial \partial z}{\partial u^2} \right), \end{aligned}$$

$$\begin{aligned} \text{III. } \left( \frac{\partial \partial z}{\partial y^2} \right) &= \frac{\partial Q}{\partial y} \left( \frac{\partial z}{\partial t} \right) + \frac{\partial S}{\partial y} \left( \frac{\partial z}{\partial u} \right) \\ &+ QQ \left( \frac{\partial \partial z}{\partial t^2} \right) + 2QS \left( \frac{\partial \partial z}{\partial t \partial u} \right) + SS \left( \frac{\partial \partial z}{\partial u^2} \right), \end{aligned}$$

quibus jungantur formulae differentiales primi gradus:

$$\left( \frac{\partial z}{\partial x} \right) = P \left( \frac{\partial z}{\partial t} \right) + R \left( \frac{\partial z}{\partial u} \right)$$

$$\left( \frac{\partial z}{\partial y} \right) = Q \left( \frac{\partial z}{\partial t} \right) + S \left( \frac{\partial z}{\partial u} \right).$$

Manifestum. autem est eadem hac methodo inveniri posse valores formularum differentialium tertii gradus, quae sunt  $\frac{\partial^3 z}{\partial t^3}$ ;  $\frac{\partial^3 z}{\partial t^2 \partial u}$ ;  $\frac{\partial^3 z}{\partial t \partial u^2}$ ;  $\frac{\partial^3 z}{\partial u^3}$ . Atque adeo ulterius progredi liceret; verum quia formulae nimis complexae essent proditurae, sufficiat methodum tantum exposuisse.

### Problema.

*Investigare casus, quibus hanc aequationem differentio-differentialem:  $(\frac{\partial \partial z}{\partial x^2}) = vv (\frac{\partial \partial z}{\partial y^2})$  generaliter integrare liceat, ope transformationis ante explicatae.*

### Solutio.

Si hic loco formularum  $(\frac{\partial \partial z}{\partial x^2})$  et  $(\frac{\partial \partial z}{\partial y^2})$  valores modo inventos substituamus, orietur sequens aequatio:

$$\begin{aligned} & \frac{\partial P}{\partial x} (\frac{\partial z}{\partial t}) + \frac{\partial R}{\partial x} (\frac{\partial z}{\partial u}) + PP (\frac{\partial \partial z}{\partial t^2}) + 2PR (\frac{\partial \partial z}{\partial t \partial u}) + RR (\frac{\partial \partial z}{\partial u^2}) \\ = & vv [\frac{\partial Q}{\partial y} (\frac{\partial z}{\partial t}) + \frac{\partial S}{\partial y} (\frac{\partial z}{\partial u}) + QQ (\frac{\partial \partial z}{\partial t^2}) + 2QS (\frac{\partial \partial z}{\partial t \partial u}) + SS (\frac{\partial \partial z}{\partial u^2})]. \end{aligned}$$

Nunc igitur quaeritur, quomodo novae variables  $t$  et  $u$  accipi oporteat, ut haec aequatio integrationem admittat. Hunc in finem efficiamus primo ut partes  $(\frac{\partial \partial z}{\partial t^2})$  se mutuo destruant, quod eveniet si fuerit  $PP = QQvv$ , ideoque  $P = \pm Qv$ . Simili modo partes  $(\frac{\partial \partial z}{\partial u^2})$  se destruent casu  $RR = SSvv$ , ideoque  $R = \pm Sv$ . Sumto autem  $P = +Qv$ , necessario sumi debet  $R = -Sv$ , quio alioquin etiam partes  $(\frac{\partial \partial z}{\partial t \partial u})$  se mutuo destruerent.



§. 11. Sumamus igitur  $P = Qv$  et  $R = -Sv$ , atque nostra aequatio inducet hanc formam:

$$\begin{aligned} & \frac{\partial \cdot Qv}{\partial x} \left( \frac{\partial z}{\partial t} \right) - \frac{\partial \cdot Sv}{\partial x} \left( \frac{\partial z}{\partial u} \right) - 2QSvv \left( \frac{\partial \partial z}{\partial t \partial u} \right) \\ &= vv \frac{\partial Q}{\partial y} \left( \frac{\partial z}{\partial t} \right) + vv \frac{\partial S}{\partial y} \left( \frac{\partial z}{\partial u} \right) + 2QSvv \left( \frac{\partial \partial z}{\partial t \partial u} \right), \end{aligned}$$

sive

$$\begin{aligned} \frac{\partial \cdot Qv}{\partial x} \left( \frac{\partial z}{\partial t} \right) - \frac{\partial \cdot Sv}{\partial x} \left( \frac{\partial z}{\partial u} \right) &= vv \frac{\partial Q}{\partial y} \left( \frac{\partial z}{\partial t} \right) + vv \frac{\partial S}{\partial y} \left( \frac{\partial z}{\partial u} \right) \\ &+ 4QSvv \left( \frac{\partial \partial z}{\partial t \partial u} \right), \end{aligned}$$

quae aequatio tribus tantum membris principalibus constat, scilicet:

$$4QSvv \left( \frac{\partial \partial z}{\partial t \partial u} \right) + \left( vv \frac{\partial Q}{\partial y} - \frac{\partial \cdot Qv}{\partial x} \right) \left( \frac{\partial z}{\partial t} \right) + \left( vv \frac{\partial S}{\partial y} + \frac{\partial \cdot Sv}{\partial x} \right) \left( \frac{\partial z}{\partial u} \right) = 0.$$

§. 12. Cum igitur sit  $P = Qv$  et  $R = -Sv$ , erit  $\partial t = Q(v\partial x + \partial y)$ , et  $\partial u = S(\partial y - v\partial x)$ ; unde patet quantitates  $Q$  et  $S$  ita accipi debere, ut hae duae formulae integrationem admittant, id quod a valore  $v$  potissimum pendet. Quo igitur a simplicissimis incipiamus, sumamus  $v = a$ , capique poterit tam  $Q = 1$  quam  $S = 1$ , unde fit  $P = a$  et  $R = -a$ ; quibus positis aequatio nostra erit  $4aa \left( \frac{\partial \partial z}{\partial t \partial u} \right) = 0$ , sive  $\left( \frac{\partial \partial z}{\partial t \partial u} \right) = 0$ ; qua ergo bis integrata habebimus  $t = ax + y$  et  $u = y - ax$ .

§. 13. Ad aequationem inventam  $\left( \frac{\partial \partial z}{\partial t \partial u} \right) = 0$  integrandam statuamus  $\left( \frac{\partial z}{\partial u} \right) = s$ , fietque  $\left( \frac{\partial s}{\partial t} \right) = 0$ , ubi sola  $t$  variabilis accipitur, existente  $u$  constante, quare integrando

ponamus  $s = \Gamma' : u$ , existente  $\int \partial u \Gamma' : u = \Gamma : u$ . Cum igitur sit  $(\frac{\partial z}{\partial u}) = s = \Gamma' : u$ , (ubi jam sola  $u$  variabilis sumitur, ita ut  $t$  pro constante habeatur), integrando habebimus  $z = \Gamma : u + \Delta : t$ , consequenter, loco  $t$  et  $u$  scriptis eorum valoribus, habebimus hujus aequationis:  $(\frac{\partial \partial z}{\partial x^2}) = a a (\frac{\partial \partial z}{\partial y^2})$  integrale completum  $z = \Gamma : (y - ax) + \Delta : (y + ax)$ , prouti quidem jam dudum constat.

§. 14. Tentemus nunc solutionem generaliore, sumendo  $v = \frac{Y}{X}$ , existentē  $X$  functione ipsius  $x$ , et  $Y$  functione ipsius  $y$ , eritque  $\partial t = \frac{Q(Y\partial x + x\partial y)}{X}$  et  $\partial u = \frac{S(X\partial y - Y\partial x)}{X}$ , quae ambae formulae integrabiles redduntur, sumendo  $Q = \frac{1}{Y}$  et  $S = \frac{1}{Y}$ ; tum enim fit  $t = \int \frac{\partial x}{X} + \int \frac{\partial y}{Y}$  et  $u = \int \frac{\partial y}{Y} - \int \frac{\partial x}{X}$ ; porro vero  $P = \frac{1}{X}$  et  $R = -\frac{1}{X}$ .

§. 15. His ergo positis aequatio nostra hanc induet formam:

$$\frac{4}{X^2} (\frac{\partial \partial z}{\partial t \partial u}) + (\frac{X' - Y'}{Y^2}) (\frac{\partial z}{\partial t}) - (\frac{X' + Y'}{X^2}) (\frac{\partial z}{\partial u}) = 0.$$

quae ducta in  $X^2$  reducitur ad hanc:

$$4 (\frac{\partial \partial z}{\partial t \partial u}) + (X' - Y') (\frac{\partial z}{\partial t}) - (X' + Y') (\frac{\partial z}{\partial u}) = 0$$

de qua aequatione observandum est, eam in genere integrabilem esse non posse, nisi alterutra forma  $(\frac{\partial z}{\partial t})$  vel  $(\frac{\partial z}{\partial u})$  evanescat. Statuamus igitur  $X' - Y' = 0$ , id quod tantum duplici modo fieri potest: 1°) scilicet quando vel  $X' = 0$  et  $Y' = 0$ , hoc est quando utraque functio  $X$  et  $Y$  est constans, ideoque etiam  $v$  constans, quem casum modo ante

expedivimus; 2<sup>o</sup>) vero quando  $X' = b$  et  $Y' = b$ , unde fit  $X = bx$  et  $Y = by$ , hincque  $v = \frac{y}{x}$ , ideoque aequatio nostra proposita est  $(\frac{\partial \partial z}{\partial x^2}) = \frac{yy}{xx} (\frac{\partial \partial z}{\partial y^2})$ , sive

$$xx (\frac{\partial \partial z}{\partial x^2}) = yy (\frac{\partial \partial z}{\partial y^2}),$$

quem ergo casum hic evolvamus.

§. 16. Cum igitur sit  $X = bx$  et  $Y = by$ , erit  $t = \frac{1}{b} lxy$  et  $u = \frac{1}{b} l \frac{y}{x}$ . Porro vero erit  $P = \frac{1}{bx}$ ;  $Q = \frac{1}{by}$ ;  $R = -\frac{1}{bx}$ ;  $S = \frac{1}{by}$ . Aequatio autem inter  $t$  et  $u$  erit  $2 (\frac{\partial t}{\partial u}) - b (\frac{\partial z}{\partial u}) = 0$ , a cujus ergo integratione tota nostra solutio pendet. Faciamus igitur, ut ante,  $(\frac{\partial z}{\partial u}) = s$ , et aequatio nostra erit:  $2 (\frac{\partial s}{\partial t}) - bs = 0$ ; ubi sola  $t$  est variabilis, ideoque  $u$  constans; quo notato erit  $2 \partial s - bs \partial t = 0$ , sive  $2 \frac{\partial s}{s} - b \partial t = 0$ , cujus integrale est  $ls - \frac{1}{2} bt = \text{Const.} = l \Gamma' : u$ , et ad numeros transeundo:  $se^{-\frac{1}{2}bt} = \Gamma' : u$ , ideoque  $s = (\frac{\partial z}{\partial u}) = e^{\frac{1}{2}bt} \Gamma' : u$ , sive posito  $b = 2c$  erit  $(\frac{\partial z}{\partial u}) = e^{ct} \Gamma' : u$ . In hac autem aequatione jam sola  $u$  est variabilis, unde fit  $\partial z = e^{ct} \partial u \Gamma' : u$ , cujus integrale manifesto est  $z = e^{ct} \Gamma : u + \Delta : t$ .

§. 17. Cum igitur sit  $t = \frac{1}{2c} lxy$ , ideoque  $e^{ct} = \sqrt{xy}$  et  $u = \frac{1}{2c} l \frac{y}{x}$ , hinc erit  $\Gamma : u = \text{funct. cuicunque } \frac{y}{x}$ , similique modo  $\Delta : t = \text{funct. cuicunque ipsius } xy$ , consequenter integrale nostrum completum erit  $z = \sqrt{xy} \Sigma : \frac{y}{x} + \Theta : xy$ ; ubi prius membrum multiplicari potest per  $\sqrt{\frac{y}{x}}$ , quo facto erit  $z = y \Sigma : \frac{y}{x} + \Theta : xy$ . Ubi observasse juvabit, cum  $\Sigma : \frac{y}{x}$  comprehendat omnes functiones nullius dimensionis

ipsarum  $x$  et  $y$ , prius membrum denotare omnes functiones ipsarum  $x$  et  $y$  unius dimensionis. Praeter hos autem duos casus modo tractatos haud patet alios exhiberi posse, quibus aequatio in problemate proposita complete integrare liceat.

### *Problema.*

*Investigare casus, quibus haec aequatio differentialis secundi gradus:  $xx \left( \frac{\partial \partial z}{\partial x^2} \right) - fxy \left( \frac{\partial \partial y}{\partial x \partial y} \right) + gyy \left( \frac{\partial \partial z}{\partial y^2} \right) = 0$  ope transformationis hic traditae complete integrari possit.*

### *Solutio.*

§. 18. Loco binarum variabilium  $x$  et  $y$ , quarum functio est  $z$ , introducantur binae aliae  $t$  et  $u$ , quarum ad illas relatio his aequationibus exprimatur:  $\partial t = P \partial x + Q \partial y$  et  $\partial u = R \partial x + S \partial y$ , atque ex formulis supra datis colligamus primo coefficientem termini  $\left( \frac{\partial \partial z}{\partial t^2} \right)$ , qui est

$$P P x x - f P Q x y + g Q Q y y.$$

Similique modo coefficientem termini  $\left( \frac{\partial \partial z}{\partial u^2} \right)$  erit

$$R R x x - f R S x y + g S S y y,$$

quos ambos evanescentes reddamus, quod quo commodius fieri queat, statuamus  $f = a + b$  et  $g = ab$ ; hocque modo prior coefficientem resolvitur in hos factores:  $(Px - aQy)(Px - bQy)$ , qui ut evanescat ponamus  $Px = aQy$ . Alter vero coeffi-

ciens in hos factores resolvitur:  $(Rx - aSy)(Rx - bSy)$ , qui ut evanescat faciamus  $Rx = bSy$ .

§. 19. Cum igitur sit  $P = \frac{aQy}{x}$  et  $R = \frac{bSy}{x}$ , formulae principales pro  $\partial t$  et  $du$  erunt:  $\partial t = Q \left( \frac{ay \partial x + x \partial y}{x} \right)$  et  $\partial u = S \left( \frac{by \partial x + x \partial y}{x} \right)$ , quae ambae fient integrabiles sumendo  $Q = \frac{1}{y}$  et  $S = \frac{1}{y}$ . Sic enim fiet  $\partial t = a \cdot \frac{\partial x}{x} + \frac{\partial y}{y}$  et  $\partial u = b \cdot \frac{\partial x}{x} + \frac{\partial y}{y}$ , unde integralia erunt  $t = alx + ly$  et  $u = blx + ly$ , sive  $t = lx^a y$  et  $u = lx^b y$ . Sumtis autem  $Q = \frac{1}{y}$  et  $S = \frac{1}{y}$ , erit  $P = \frac{a}{x}$  et  $R = \frac{b}{x}$ .

§. 20. His jam valoribus substitutis, quia termini  $\left( \frac{\partial \partial z}{\partial t^2} \right)$  et  $\left( \frac{\partial \partial z}{\partial u^2} \right)$  jam ad nihilum sunt perducti, coëfficiens termini  $\left( \frac{\partial \partial z}{\partial t \partial u} \right)$  reperietur

$$2PRxx - f(QR + PS)xy + 2gQSy y,$$

qui ob  $f = a + b$  et  $g = ab$ , facta substitutione litterarum majuscularum, fit  $4ab - (a + b)^2 = -(a - b)^2$ , ita ut hic terminus jam sit  $-(a - b)^2 \left( \frac{\partial \partial z}{\partial t \partial u} \right)$ . Porro vero termini  $\left( \frac{\partial z}{\partial t} \right)$  coëfficiens erit  $xx \frac{\partial P}{\partial x} - fxy \frac{\partial Q}{\partial x} + gyy \frac{\partial Q}{\partial y}$ , qui ob  $\frac{\partial P}{\partial x} = \frac{-a}{xx}$ ,  $\frac{\partial Q}{\partial x} = 0$  et  $\frac{\partial Q}{\partial y} = \frac{-1}{yy}$  abit in hanc formam:  $-a(b + 1)$ . Similique modo coëfficiens termini  $\left( \frac{\partial z}{\partial u} \right)$  colligitur fore  $xx \left( \frac{\partial R}{\partial x} \right) - fxy \frac{\partial S}{\partial x} + gyy \frac{\partial S}{\partial y} = -b(a + 1)$ .

§. 21. Aequatio igitur resolvenda nunc hanc induet formam:

$$(a - b)^2 \left( \frac{\partial \partial z}{\partial t \partial u} \right) + a(b + 1) \left( \frac{\partial z}{\partial t} \right) + b(a + 1) \left( \frac{\partial z}{\partial u} \right) = 0,$$

de qua antem ante omnia notari oportet, eam nullo modo adhuc cognito tractari posse, nisi alteruter posteriorum terminorum evanescat. Statuamus igitur  $b = -1$ ; unde fit  $f = a - 1$ ;  $g = -a$  et  $t = lx^a y$  et  $u = l \frac{y}{x}$ . Aequatio vero resolvenda erit  $(a+1)^2 \left( \frac{\partial \partial z}{\partial t \partial u} \right) - (a+1) \left( \frac{\partial z}{\partial u} \right) = 0$ . Hinc ergo si ponamus  $\left( \frac{\partial z}{\partial u} \right) = v$ , ob  $\left( \frac{\partial \partial z}{\partial t \partial u} \right) = \left( \frac{\partial v}{\partial t} \right)$ , erit  $(a+1)^2 \left( \frac{\partial v}{\partial t} \right) = (a+1)v$ , sive  $(a+1) \left( \frac{\partial v}{\partial t} \right) = v$ , ubi littera  $u$  tanquam constans est spectanda, quo observato erit  $(a+1) \partial v = v \partial t$ , ideoque  $\frac{\partial v}{v} = \frac{\partial t}{a+1}$ , unde fit  $lv = \frac{t}{a+1} + lf:u$ , sicque numeris sumtis erit:  $v = e^{\frac{t}{a+1}} \Gamma':u$ .

§. 22. Cum igitur posuerimus  $v = \frac{\partial z}{\partial u}$ , ita ut nunc  $t$  pro constante sit habenda, erit:  $\frac{\partial z}{\partial u} = e^{\frac{t}{a+1}} \Gamma':u$ , sive  $\partial z = e^{\frac{t}{a+1}} \partial u \Gamma':u$ , unde ob  $\int \partial u \Gamma':u = \Gamma:u$  habebimus  $z = e^{\frac{t}{a+1}} \Gamma:u + \Delta:t$ , quae expressio, ob binas functiones arbitrarias, utique praebet integrale completum aequationis propositae, casu scilicet quo  $f = a - 1$  et  $g = -a$ .

§. 23. Quo nunc hanc formam ad variables  $x$  et  $y$  transferamus, notemus primo esse:  $t = lx^a y$ , unde fit  $e^t = x^a y$ , hincque  $e^{\frac{t}{a+1}} = x^{\frac{a}{a+1}} y^{\frac{1}{a+1}} = \sqrt[a+1]{x^a y}$ ; tum vero functio quaecunque ipsius  $t$  erit etiam functio quaecunque ipsius  $x^a y$ , unde pro  $\Delta:t$  scribere licebit  $\Delta:x^a y$ . Deinde cum sit  $u = l \frac{y}{x}$ , ejus functio quaecunque etiam

erit functio ipsius  $\frac{y}{x}$ , sicque loco  $\Gamma:u$  nunc habebimus  $\Gamma:\frac{y}{x}$ . Hinc hujus aequationis differentio-differentialis:

$$xx\left(\frac{\partial\partial z}{\partial x^2}\right) - (a-1)xy\left(\frac{\partial\partial z}{\partial x\partial y}\right) - ay^2\left(\frac{\partial\partial z}{\partial y^2}\right) = 0,$$

integrale completum erit:  $z = \sqrt[a+1]{x^a y} \Gamma:\frac{y}{x} + \Delta:x^a y$ .

Quoniam igitur ista aequatio abit in eam quam praecedente problemate invenimus casu  $a=1$ , eadem forma integralis prodibit, quam supra (§. 17.) invenimus, scilicet:

$$z = \sqrt{x y} \Gamma:\frac{y}{x} + \Delta:xy.$$

§. 24. Prius membrum illius formae integralis multo simplicius exprimi potest, dum scil. ejus factor prior per quandam functionem ipsius  $\frac{y}{x}$  multiplicatur vel dividatur. Dividatur ergo per  $\sqrt[a+1]{\frac{y}{x}}$ , prodibit  $z = x \Gamma:\frac{y}{x} + \Delta:x^a y$ ; ubi notandum est prius membrum  $x \Gamma:\frac{y}{x}$  continere omnes functiones homogeneas unius dimensionis ipsarum  $x$  et  $y$ . Observetur hic, si etiam fuerit  $x = -1$ , ita ut aequatio proposita sit  $xx\left(\frac{\partial\partial z}{\partial x^2}\right) - 2xy\left(\frac{\partial\partial z}{\partial x\partial y}\right) + y^2\left(\frac{\partial\partial z}{\partial y^2}\right) = 0$ , tum integrale completum fore  $z = x \Gamma:\frac{y}{x} + \Delta:\frac{y}{x}$ . Ubi notandum, etiamsi duae functiones ejusdem formae  $\frac{y}{x}$  occurrant, eas in unam contrahi non posse, propterea quod prior multiplicata est per  $x$ .

